

<b>Module description: Control Engineering Fundamentals</b>			
<b>Module Code</b>	t.BA.XX.RT.19HS		
<b>ECTS Credits</b>	4		
<b>Language of Instruction/Examination</b>	German		
<b>Organizational Unit</b>	IMS		
<b>Module Coordinator</b>	Konrad Stadler		
<b>Legal Framework</b>	The module description is part of the legal basis in addition to the general academic regulations. It is binding. During the first week of the semester a written and communicated supplement can specify the module description in more detail.		
<b>Module Characteristic</b>	Type 3b  2 lecture lessons per semester week and class+ 4 lab bi-weekly lessons per semester and half-class		
<b>Module Description</b>	Students are able to analyse and interpret closed loop dynamic systems in the time and frequency domain.		
<b>Module Content</b>	<p><b>Lecture:</b></p> <p><b>Laplace transformation focusing on transfer function, pole zero map and time and frequency behaviour.</b></p> <p><b>System representation as block diagrams and block diagram algebra.</b></p> <p><b>Feedback and difference between open loop and closed loop.</b></p> <p><b>Modelling of dynamic systems.</b></p> <p><b>Stability of linear time invariant systems.</b></p> <p><b>Design of PID controller</b></p> <p><b>Frequency response method</b></p> <p><b>Laboratory course:</b></p> <p><b>Specific experiments are conducted by the students to reinforce their understanding of the theoretical concepts.</b></p>		
<b>Prerequisite Knowledge</b>	Signals and systems		
<b>Learning Objectives (Competences)</b>	<b>Students...</b>	<b>Competencies</b>	<b>Taxonomies</b>
	Students can assess the stability of systems in the time and in the frequency domain.	F, M	K3
	Students are able to describe dynamic systems based on first principles and can derive a mathematical model of the system.	F, M	K3
	Students understand the concept of feedback.	M, F	K3
	Students can understand and apply basic methods to design PID controllers.	M, F	K3

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<b>Performance Assessment</b>	<b>End-of-module exam</b>	<b>Assessment</b>	<b>Length (min.)</b>	<b>Weighting</b>	<b>Form</b>	
	written exam	Grade	90	80	acc. to module agreement	
	<b>Performance assessment during the semester</b>		<b>Assessment</b>	<b>Length (min.)</b>	<b>Weighting</b>	<b>Form</b>
	written exam		Grade	45	20	acc. to module agreement
<b>Classroom Attendance Requirement</b>	None The labs are compulsory.					
<b>Learning material</b>	<ul style="list-style-type: none"> <li>• Franklin, G. &amp; Powell, J. &amp; Emami-Naeini, A. (2020). Feedback control of dynamic systems. 8. Edition. Harlow, England : Pearson Education Limited. ISBN 9781292274522 .</li> <li>• Lecture notes</li> <li>• Zacher , S. &amp; Reuter , M. (2022). Regelungstechnik für Ingenieure: Analyse, Simulation und Entwurf von Regelkreisen. 16 Edition. Springer. ISBN 9783658364069.</li> <li>• Lunze, J. (2020). Regelungstechnik 1: Systemtheoretische Grundlagen, Analyse und Entwurf einschleifiger Regelungen . 12 Edition. Berlin Heidelberg: Springer . ISBN 9783662607459.</li> </ul>					
<b>Comments</b>	Labs are compulsory!					